

1. (20%) Please answer the following questions with explanations
- (a) When we pass a baseband signal sample to a quantizer, often the compression law of either  $\mu$ -law or A-law is used. What is the purpose of using the compressor? (4%)
  - (b) Consider a binary digital transmission system in which the transmitted signal is modulated with FSK as

$$s_i(t) = \sqrt{\frac{2E}{T}} \cos(2\pi f_i t), 0 \leq t \leq T, i = 1, 2 \quad (1)$$

- What is the basic difference between coherent binary FSK and non-coherent binary FSK (i.e. what does coherent or non-coherent mean)? Please draw the block diagram of the binary FSK receiver for coherent and non-coherent binary FSK respectively. (4%)
- (c) Considering the coherent binary FSK system, as defined in Eq. (1), symbols of 1 and 0 are distinguished from each other by transmitting one of two sinusoidal waves that differ in orthogonal frequencies. What is the frequency spacing of  $f_1$  and  $f_2$  for achieving the best spectral efficiency utilization? (4%)
  - (d) What is the desired autocorrelation property of the pseudo-random sequence for the application in the direct sequence spread spectrum communication? (4%)
  - (e) Two passband data transmission systems are to be compared. One system uses 16-PSK and the other uses 16-QAM for modulation. Both systems are required to produce the same symbol error rate. Please compare the signal-to-noise ratio requirement of these two systems. (4%)

2. (15%) Consider a baseband binary data transmission system as shown in Fig. A.

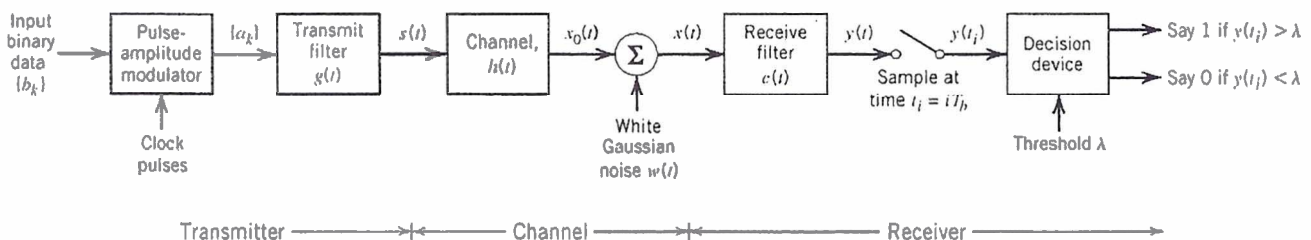


Figure A. Baseband data transmission system

The incoming binary system sequence  $\{b_k\}$  consists of symbols 1 and 0, each of duration  $T_b = 0.5\mu\text{s}$ . The PAM modifies  $\{b_k\}$  into  $\{a_k\}$ , where

$$a_k = \begin{cases} +1, & \text{if } b_k = 1 \\ -1, & \text{if } b_k = 0 \end{cases}$$

The receiver filter output is

$$y(t) = \sum_k a_k p(t - kT_b) + n(t)$$

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where

$$p(t) = g(t) * h(t) * c(t)$$

(Hint: The Fourier series transform pair:  $\sum_{k=-\infty}^{\infty} p(t - kT_b) \xleftrightarrow{F.T.} \frac{1}{T_b} \sum_{n=-\infty}^{\infty} P\left(f - \frac{n}{T_b}\right)$ )

- (a) Please derive and find the condition such that the decision device input  $y(t_i)$  is ISI (inter-symbol-interference) free. (10%)
- (b) Let the frequency response of  $p(t)$  be in the form of a rectangular function. Please find the highest frequency component of  $P(f)$ . (5%)

3. (20%) A random process defined by

$$X(t) = A(t) \cos(2\pi f_c t + \Theta),$$

is applied to an integrator producing the output

$$Y(t) = \int_{t-T}^t X(\tau) d\tau$$

- (a) Suppose that  $f_c$  is a constant,  $A(t)$  is a wide-sense stationary random process independent of  $\Theta$ , and  $\Theta$  is a random variable uniformly distributed in  $[0, 2\pi]$ . We denote the power spectral density of  $A(t)$  by  $S_A(f)$ . Show that the power spectral density  $S_Y(f)$  of  $Y(t)$  is given by

$$S_Y(f) = \frac{1}{4} [S_A(f - f_c) + S_A(f + f_c)] T^2 \text{sinc}^2(Tf)$$

(8%)

- (b) Suppose that  $f_c$  is a constant,  $A(t) = A$ , where  $A$  is a Gaussian distributed random variable of zero mean and variance  $\sigma_A^2$ , and  $\Theta = 0$ . Determine the probability density function of the output  $Y(t)$  at a particular time  $t_k$ . (4%)
- (c) Based on the assumption in (b), is  $Y(t)$  stationary? Give your reason. (4%)
- (d) Based on the assumption in (b), is  $Y(t)$  ergodic? Give your reason. (4%)

4. (15%) In a binary antipodal signalling scheme, the signals are given by

$$s_1(t) = -s_2(t) = \begin{cases} 2At/T, & 0 \leq t \leq T/2 \\ 2A(1 - t/T), & T/2 \leq t \leq T \\ 0, & \text{otherwise} \end{cases}$$

The channel is AWGN, and its power spectral density is  $N_0/2$ . The two signals  $s_1(t)$  and  $s_2(t)$  have prior probabilities  $p_1$  and  $p_2 = 1 - p_1$ , respectively.

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- (a) What is the impulse response of the matched filter? (2%)
- (b) Given that  $s_1(t)$  was sent, what is the probability density function of the output of the matched filter? (4%)
- (c) Let the threshold of the decision device be  $\lambda$ . Express the average error probability in terms of  $\lambda$ . (4%)
- (d) What is the optimal value of  $\lambda$  yielding the minimum average error probability? (5%)

5. (20%) In this problem, we consider the Alamouti code used for multi-input and multi-output (MIMO) fading channels. Two transmit antennas and one receive antenna are considered in this problem. Let us assume an  $M$ -ary ( $M$ -PSK or  $M$ -QAM) modulation scheme is used. In the Alamouti encoder, each group of  $m$  information bits is first modulated, where  $m = \log_2 M$ . Then, the encoder takes a block of two modulated symbols  $x_1$  and  $x_2$  in each encoding operation and maps them to the transmit antennas. A codeword transmits across two consecutive symbol transmission periods. Let us denote the transmit sequences from antennas one and two are given by  $\mathbf{x}^1 = [x_1, -x_2^*]$  and  $\mathbf{x}^2 = [x_2, x_1^*]$ , respectively, where  $*$  denotes the complex conjugate operation.

(a) Show that the transmit sequences from the two transmit antennas are orthogonal. (1%)

(b) Let the fading coefficients from antennas one and two be  $h_1$  and  $h_2$ , respectively. Assume these fading coefficients are constant across two consecutive symbol transmission periods. At the receive antenna, the received signal over two consecutive symbol periods, denoted by  $r_1$  and  $r_2$ , can be expressed as  $r_1 = h_1 x_1 + h_2 x_2 + n_1$ ;  $r_2 = h_2 x_1^* - h_1 x_2^* + n_2$ , where  $n_1$  and  $n_2$  are independent complex Gaussian random variables with zero mean and power spectral density  $N_0/2$  per dimension, representing the additive white Gaussian noise. For  $i = 1, 2$ , write  $n_i = n_{i,x} + j n_{i,y}$ , where  $n_{i,x}$  and  $n_{i,y}$  are independent real Gaussian random variables with zero mean and variance  $\sigma^2$  and  $j = \sqrt{-1}$ . Assume that the channel fading coefficients  $h_1$  and  $h_2$ , can be perfectly recovered at the receiver. Then, the decoder chooses a pair of signal  $[\hat{x}_1, \hat{x}_2]$  from the signal constellation to minimize the distance metric  $|r_1 - (h_1 \hat{x}_1 + h_2 \hat{x}_2)|^2 + |r_2 - (h_2 \hat{x}_1^* - h_1 \hat{x}_2^*)|^2$  over all possible  $[\hat{x}_1, \hat{x}_2]$ . Show that the decision rule becomes

$$\hat{x}_1 = \arg \min_{\hat{x}_1 \in S} (|h_1|^2 + |h_2|^2 - 1) |\hat{x}_1|^2 + d^2(\tilde{x}_1, \hat{x}_1)$$

$$\hat{x}_2 = \arg \min_{\hat{x}_2 \in S} (|h_1|^2 + |h_2|^2 - 1) |\hat{x}_2|^2 + d^2(\tilde{x}_2, \hat{x}_2),$$

where  $\tilde{x}_1 = h_1^* r_1 + h_2 r_2^*$ ,  $\tilde{x}_2 = h_2^* r_1 - h_1 r_2^*$ ,  $d^2(\tilde{x}_i, \hat{x}_i) = |\tilde{x}_i - \hat{x}_i|^2$ ,  $i = 1, 2$ , and  $S$  is the set of all possible modulated signal points in an  $M$ -ary signal constellation. (10%)

(c) Show that the decision rule in (b) becomes

$$\hat{x}_1 = \arg \min_{\hat{x}_1 \in S} d^2(\tilde{x}_1, \hat{x}_1)$$

$$\hat{x}_2 = \arg \min_{\hat{x}_2 \in S} d^2(\tilde{x}_2, \hat{x}_2),$$

if  $M$ -PSK constellations are used. (1%)

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- (d) Show that the decoder used in (b) is a maximum likelihood decoder. (8%)
6. (10%) In this problem, we consider differential PSK (DPSK). Let  $m(k)$  be a message data stream, where  $k$  is the sample time index. Let the sequence of encoded bits,  $c(k)$ , be encoded by using the following way:  $c(k) = \overline{c(k-1)} \oplus m(k)$ , where the symbol  $\oplus$  represents modulo-2 addition and the overbar denotes complement.
- (a) Show that the first bit of the code bit sequence,  $c(k=0)$ , can be chosen arbitrarily without affecting the detected message sequence at receiver. (1%)
- (b) Please draw the block diagrams for DPSK transmitter and DPSK receiver. (3%)
- (c) Please describe the decision rules in your DPSK receiver. Please also give the reasons of choosing such decision rules. (6%)